# API Arm - 7 Axis Portable Measuring Arm

### FEATURES & BENEFITS

The API Arm provides an ideal combination of contact and non-contact measurement. The innovative design utilizes advanced materials to provide a reliable, portable, and lightweight coordinate measuring machine.

#### Simple Operation

Carbon fiber tubes, ergonomic handle, and integrated counterbalance allow scanning with minimal effort.

#### True Portability

With an integrated battery, WiFi connection, and temperature regulation the arm can perform wherever you need it.

#### Extended Global Measurement Volume

The API Arm can be paired with an API Laser Tracker to extend the overall working volume of the system while maintaining the highest level of accuracy.

#### Magnetic Docking

The handle of the arm conveniently attaches to the body when not in use.

#### Multiple Sizes Available

The API Arm is available in 2m, 2.5m, 3m, 4m, and 4.5m sizes to provide the perfect fit for your application.



#### SKYLINE-SCANNER

The Skyline scanner is an excellent solution for 3D analysis. High speed scanning and 200mm laser line allows you to detect the smallest details in This scanner integrates into the bandle with a quick

record time. This scanner integrates into the handle with a quick detach feature.



PROBE CONNECTIVITY

A probe can be connected directly to the handle for contact measurement. The available probes have auto detection for quick setup. <u>co</u>

COMMON APPLICATIONS

- Dimensional Analysis
- Rapid Prototyping
- First Article Inspection
- Reverse Engineering
  Surface Acquisition

### TRACKED ARM FOR LARGE PART INSPECTION



- Allows the possibility to use a portable arm to measure large parts (up to 80m). The long range and precision of the API Radian laser tracker adds versatility, flexibility and accuracy to the combination portable measuring solution.
- Overall precision results from the volumetric accuracy of the arm during local measurements, and subsequent ly from the laser tracker alignment precision.
- The measuring arm is placed on a tripod and moved around the large part in order to measure in several measurement stages. The tracker follows its move ments through SMRs placed on the arm. Each position is stored and then associated to the previous ones to obtain a single coordinate system.
- The solution is suited to automotive, aerospace, and energy industries as well as large parts suppliers nee ding both portability and precision.

## TECHNICAL FEATURES

#### **Technical Specifications**

| Axis | Working Volume | E <sub>UNI</sub> * | P <sub>SIZE</sub> * | P <sub>FORM</sub> * | L <sub>DIA</sub> * | S <sub>PAT</sub> * |
|------|----------------|--------------------|---------------------|---------------------|--------------------|--------------------|
| 7    | 2m             | 0.037 mm           | 0.012 mm            | 0.020 mm            | 0.044 mm           | 0.022 mm           |
| 7    | 2.5m           | 0.041 mm           | 0.015 mm            | 0.024 mm            | 0.055 mm           | 0.027 mm           |
| 7    | 3m             | 0.069 mm           | 0.020 mm            | 0.035 mm            | 0.081 mm           | 0.042 mm           |
| 7    | 3.5m           | 0.079 mm           | 0.024 mm            | 0.041 mm            | 0.095 mm           | 0.054 mm           |
| 7    | 4m             | 0.094 mm           | 0.029 mm            | 0.048 mm            | 0.115 mm           | 0.066 mm           |
| 7    | 4.5m           | 0.114 mm           | 0.045 mm            | 0.060 mm            | 0.125 mm           | 0.078 mm           |

\*All specifications are subject to change without notification

#### According to ISO 10360-12, 2016:

E<sub>UNI</sub> (EUni:0:Tact.AArm): Unidirectional distance error between two probed points in the arm volume P<sub>SIZE</sub> (PSize.Sph.1x25:Tact.AArm): Error on the measurement of a sphere diameter by probing P<sub>FORM</sub> (PForm.Sph.1x25:Tact.AArm): Dispersion value in measurement of a sphere radius by probing LDIA (LDIa.5x5:Art:Tact.AArm): Errors due to arm articulations, mainly axes 5, 6 and 7 of the wrist, measured with probe

 $\mathsf{S}_{\mathsf{PAT}}$  . Measurement error when the probe is stationary and the arm elbow moves from left to right

According to ISO 10360-8:2013:

 $L_{DIA}$  scanning (LDia; ODS) : Errors due to arm articulations, mainly axes 5, 6 and 7 of the wrist, measured with scanner

\*1 MPE (P[Size.Sph.All:Tr:ODS]): Error on the measurement of a sphere diameter by Scanning \*2 MPL (P[Form.Sph.D95%:Tr:ODS]): dispersion value on 95% of the measured points on a sphere

\*3 MPL (P[Form.Pla.D95%:Tr:ODS]): dispersion value on 95% of the measured points on a plane

| 3D Scanner Specifications |                     |                     |                     |
|---------------------------|---------------------|---------------------|---------------------|
|                           | ACE SKYLINE<br>EYES | ACE SKYLINE<br>WIDE | ACE SKYLINE<br>OPEN |
| Max. Scanning Speed       | 600,000 pts/sec     | 600,000 pts/sec     | 200,000 pts/sec     |
| Accuracy                  | ±9μm                | ± 15 μm             | ± 20 μm             |
| Max. Laser Line Width     | 100mm               | 200mm               | 100mm               |
| Max. Frequency            | 300Hz               | 300Hz               | 200Hz               |
| Laser Class               | Blue, Class 2M      | Blue, Class 2M      | Blue, Class 2M      |
| Line Resolution           | 25 µm               | 50 µm               | 50 µm               |
| Stand-off Distance        | 90mm                | 85mm                | 85mm                |
| Field of View             | 80mm                | 110mm               | 110mm               |
| LED Indicators            | YES                 | YES                 | NO                  |
| Temperature Compensation  | YES                 | YES                 | NO                  |



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